



Low Voltage alternators - 4 pole LSA 40

10 to 23 kVA - 50 Hz / 12.5 to 28 kVA - 60 Hz

Electrical and mechanical data

4250 en - 2014.01 / f

Low Voltage alternators 4 pole 3-phase *PARTNER*

LSA 40

10 to 23 kVA - 50 Hz / 12.5 to 28 kVA - 60 Hz

SPECIALLY ADAPTED TO APPLICATIONS

The LSA 40 alternator is designed to be suitable for typical generator applications, such as: backup, marine applications, rental, telecommunications, etc.

COMPLIANT WITH INTERNATIONAL STANDARDS

The LSA 40 alternator conforms to the main international standards and regulations:

- IEC 60034, NEMA MG 1.32-33, ISO 8528/3, CSA, UL 1446, UL 1004 on request, marine regulations, etc.

It can be integrated into a CE marked generator.

The LSA 40 is designed, manufactured and marketed in an ISO 9001 environment.

TOP OF THE RANGE ELECTRICAL PERFORMANCE

- Class H insulation.
- Standard 12 wire re-connectable winding, 2/3 pitch, type no. 6.
- Voltage range:
 - 50 Hz: 220 V - 240 V and 380 V - 415 V (440 V)
 - 60 Hz: 208 V - 240 V and 380 V - 480 V
- High efficiency and motor starting capacity.
- Other voltages are possible with optional adapted windings:
 - 50 Hz: 440 V (no. 7), 500 V (no. 9),
 - 60 Hz: 380 V and 416 V (no. 8), 600 V (no. 9)
- R 791 interference suppression conforming to standard EN 55011 group 1 class B standard for European zone (CE marking).

EXCITATION AND REGULATION SYSTEM SUITED TO THE APPLICATION

Excitation system			Regulation options			
Voltage regulator	SHUNT	AREP	Current transformer for paralleling	Mains paralleling	3-phase sensing	Remote voltage potentiometer
R220	Std	-	-	-	-	-
R438	-	Std	C.T.*	R726*	R731*	√
D510C*	Option	Option	C.T.*	included	included	√

AVR voltage accuracy $\pm 1\%$

√: Possible mounting

* External mounting

PROTECTION SYSTEM SUITED TO THE ENVIRONMENT

- The LSA 40 is IP 23.
- Standard winding protection for clean environments with relative humidity $\leq 95\%$, including indoor marine environments.
- Options:
 - filters on air inlet : derating 5%,
 - filters on air inlet and air outlet (IP 44) : derating 10%,
 - winding protection for harsh environments and relative humidity greater than 95%,
 - space heaters,
 - thermal protection for stator windings,
 - steel terminal box.

REINFORCED MECHANICAL STRUCTURE USING FINITE ELEMENT MODELLING

- Compact rigid assembly to better withstand generator vibrations.
- Steel frame.
- Aluminium flanges and shields.
- Two-bearing and single-bearing versions designed to be suitable for commercially-available heat engines.
- Half-key balancing.
- Permanently greased bearings.
- Direction of rotation : clockwise and anti-clockwise (without derating).

ACCESSIBLE TERMINAL BOX

- Easy access to the AVR and to the connections.
- 8 way terminal block for reconnecting the voltage.
- Predrilled holes for cable gland.



Low Voltage alternators 4 pole 3-phase *PARTNER*

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10 to 23 kVA - 50 Hz / 12.5 to 28 kVA - 60 Hz

General characteristics

Insulation class	H	Excitation system	SHUNT	AREP
Winding pitch	2/3 (wdg 6)	AVR type	R 220	R 438
Number of wires	12	Voltage regulation (*)	± 1%	± 0.5%
Protection	IP 23	Short-circuit current	-	300% (3 IN): 10 s
Altitude	≤ 1000 m	Totale Harmonic distortion THD (**) in no-load : < 3% according to IEC		
Overspeed	2250 min ⁻¹	Totale Harmonic distortion THD (**) on linear load : < 5% according to IEC		
Air flow	0.06 m ³ /s, 50 Hz - 0.072 m ³ /s, 60 Hz	Waveform: NEMA = TIF (**) < 50		

(*) Steady state. (**) Total harmonic distortion between phases, in no-load or on linear load.

Ratings 50 Hz - 1500 R.P.M.

kVA / kW - P.F. = 0.8																					
Duty/T°C		Continuous duty/40°C					Continuous duty/40°C					Stand-by/40°C					Stand-by/27°C				
Class/T°K		H/125°K					F/105°K					H/150°K					H/163°K				
Phase		3 ph.			1 ph.		3 ph.			1 ph.		3 ph.			1 ph.		3 ph.			1 ph.	
Y		380V	400V	415V	440V	ΔΔ	380V	400V	415V	440V	ΔΔ	380V	400V	415V	440V	ΔΔ	380V	400V	415V	440V	ΔΔ
Δ		220V	230V	240V		230V	220V	230V	240V		230V	220V	230V	240V		230V	220V	230V	240V		230V
YY					220V					220V					220V					220V	
40 VS1	kVA	10	10	10	9	7	9	9	9	8	6.5	10.5	10.5	10.5	9	7.5	11	11	11	10	8
	kW	8	8	8	7.2	5.6	7.2	7.2	7.2	6.4	5.2	8.4	8.4	8.4	7.2	6	8.8	8.8	8.8	8	6.4
40 VS2	kVA	12.5	12.5	12.5	11	9	11.5	11.5	11.5	10	8	13.5	13.5	13.5	12	9.5	14	14	14	12.5	10
	kW	10	10	10	8.8	7.2	9.2	9.2	9.2	8	6.4	10.8	10.8	10.8	9.6	7.6	11.2	11.2	11.2	10	8
40 S3	kVA	15	15	15	13	10.5	14	14	14	12	10	16	16	16	14	11.5	16.5	16.5	16.5	15	12
	kW	12	12	12	10.4	8.4	11.2	11.2	11.2	9.6	8	12.8	12.8	12.8	11.2	9.2	13.2	13.2	13.2	12	9.6
40 S4	kVA	17.5	17.5	17.5	16	12.5	16	16	16	14	11.5	19	19	19	16.5	13.5	19.5	19.5	19.5	17	14
	kW	14	14	14	12.8	10	12.8	12.8	12.8	11.2	9.2	15.2	15.2	15.2	13.2	10.8	15.6	15.6	15.6	13.6	11.2
40 M5	kVA	20	20	20	18	14	18.5	18.5	18.5	16	13	21.5	21.5	21.5	19	15	22	22	22	20	15.5
	kW	16	16	16	14.4	11.2	14.8	14.8	14.8	12.8	10.4	17.2	17.2	17.2	15.2	12	17.6	17.6	17.6	16	12.4
40 L7	kVA	23	23	23	19	15	20	20	20	16	14	24	24	24	20	16	25	25	25	22	16.5
	kW	18.4	18.4	18.4	15.2	12	16	16	16	12.8	11.2	19.2	19.2	19.2	16	12.8	20	20	20	17.6	13.2

Ratings 60 Hz - 1800 R.P.M.

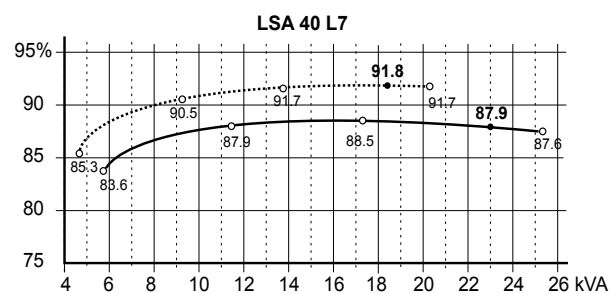
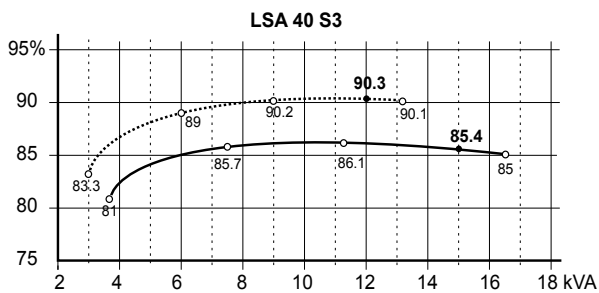
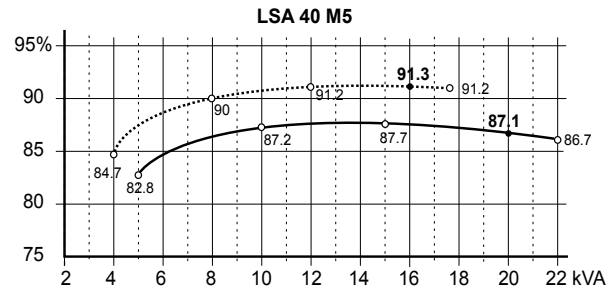
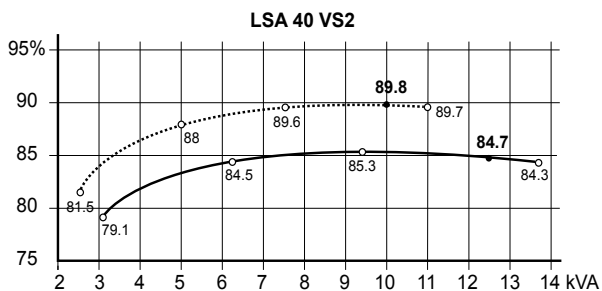
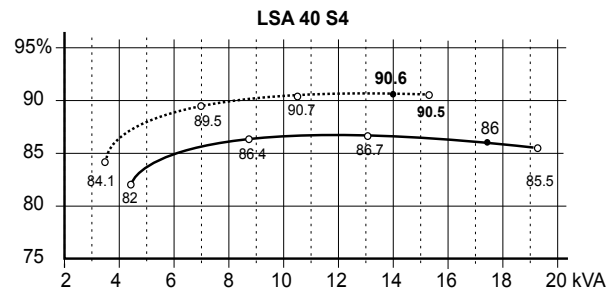
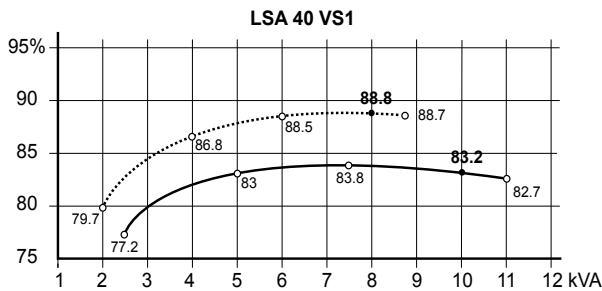
kVA / kW - P.F. = 0.8																					
Duty/T°C		Continuous duty/40°C					Continuous duty/40°C					Stand-by/40°C					Stand-by/27°C				
Class/T°K		H/125°K					F/105°K					H/150°K					H/163°K				
Phase		3 ph.			1 ph.		3 ph.			1 ph.		3 ph.			1 ph.		3 ph.			1 ph.	
Y		380V	416V	440V	480V	ΔΔ	380V	416V	440V	480V	ΔΔ	380V	416V	440V	480V	ΔΔ	380V	416V	440V	480V	ΔΔ
Δ		220V	240V			240V	220V	240V			240V	220V	240V			240V	220V	240V			240V
YY		208V 220V 240V					208V 220V 240V					208V 220V 240V					208V 220V 240V				
40 VS1	kVA	10	11	11.5	12.5	9	9.5	10.5	10.5	11.5	8.5	11	11.5	12.5	13.5	9.5	11.5	12	13	14	10
	kW	8.0	8.8	9.2	10.0	7.2	7.6	8.4	8.4	9.2	6.8	8.8	9.2	10	10.8	7.6	9.2	9.6	10.4	11.2	8
40 VS2	kVA	12.5	13.5	14.5	15.5	11.5	11.5	12.5	13.5	14.5	10.5	13.5	14.5	15.5	16.5	12	14	15	16	17	12.5
	kW	10.0	10.8	11.6	12.4	9.2	9.2	10	10.8	11.6	8.4	10.8	11.6	12.4	13.2	9.6	11.2	12	12.8	13.6	10
40 S3	kVA	15	16.5	17.5	19	13	14	15.5	16.5	17.5	12	16	18	19	20	13.5	17	18.5	19.5	21	14
	kW	12	13.2	14.0	15.2	10.4	11.2	12.4	13.2	14	9.6	12.8	14.4	15.2	16	10.8	13.6	14.8	15.6	16.8	11.2
40 S4	kVA	17.5	19	20	22	14.5	16.5	18	19	20.5	13	19	20.5	21.5	23.5	15	19.5	21	22	24.5	15.5
	kW	14.0	15.2	16.0	17.6	11.6	13.2	14.4	15.2	16.4	10.4	15.2	16.4	17.2	18.8	12	15.6	16.8	17.6	19.6	12.4
40 M5	kVA	20	22	23	25	16	18.5	20.5	21.5	23	15	21.5	23.5	25	27	17	22	24.5	26	27.5	17.5
	kW	16	17.6	18.4	20	12.8	14.8	16.4	17.2	18.4	12.0	17.2	18.8	20	21.6	13.6	17.6	19.6	20.8	22	14
40 L7	kVA	22	24.5	25.5	28	17.5	20.5	23	24	25	15.5	24	26	27.5	30	18.5	24.5	27	28.5	31	19.5
	kW	17.6	19.6	20.4	22.4	14	16.4	18.4	19.2	20	12.4	19.2	20.8	22	24	14.8	19.6	21.6	22.8	24.8	15.6

Low Voltage alternators 4 pole 3-phase *PARTNER*

LSA 40

10 to 23 kVA - 50 Hz / 12.5 to 28 kVA - 60 Hz

Efficiencies 50 Hz (— P.F.: 0.8) (..... P.F.: 1)



Reactances (%). Time constants (ms) - Class H / 400 V

	VS1	VS2	S3	S4	M5	L7
Kcc Short-circuit ratio	0.72	0.69	0.62	0.62	0.63	0.63
Xd Direct-axis synchro. reactance unsaturated	167	174	190	195	193	192
Xq Quadrature-axis synchro. reactance unsaturated	100	104	114	117	116	115
T'do No-load transient time constant	780	858	909	953	1006	1072
X'd Direct-axis transient reactance saturated	17.2	16.3	16.8	16.4	15.4	14.4
T'd Short-circuit transient time constant	74	74	74	74	74	74
X''d Direct-axis subtransient reactance saturated	8.6	8.1	8.4	8.2	7.7	7.2
T''d Subtransient time constant	7	7	7	7	7	7
X''q Quadrature-axis subtransient reactance saturated	16.1	15.9	16.8	16.8	16.2	15.6
Xo Zero sequence reactance unsaturated	0.1	0.1	0.1	0.1	0.1	0.1
X2 Negative sequence reactance saturated	12.4	12.0	12.7	12.6	12.0	11.4
Ta Armature time constant	11	11	11	11	11	11

Other class H/400 V data

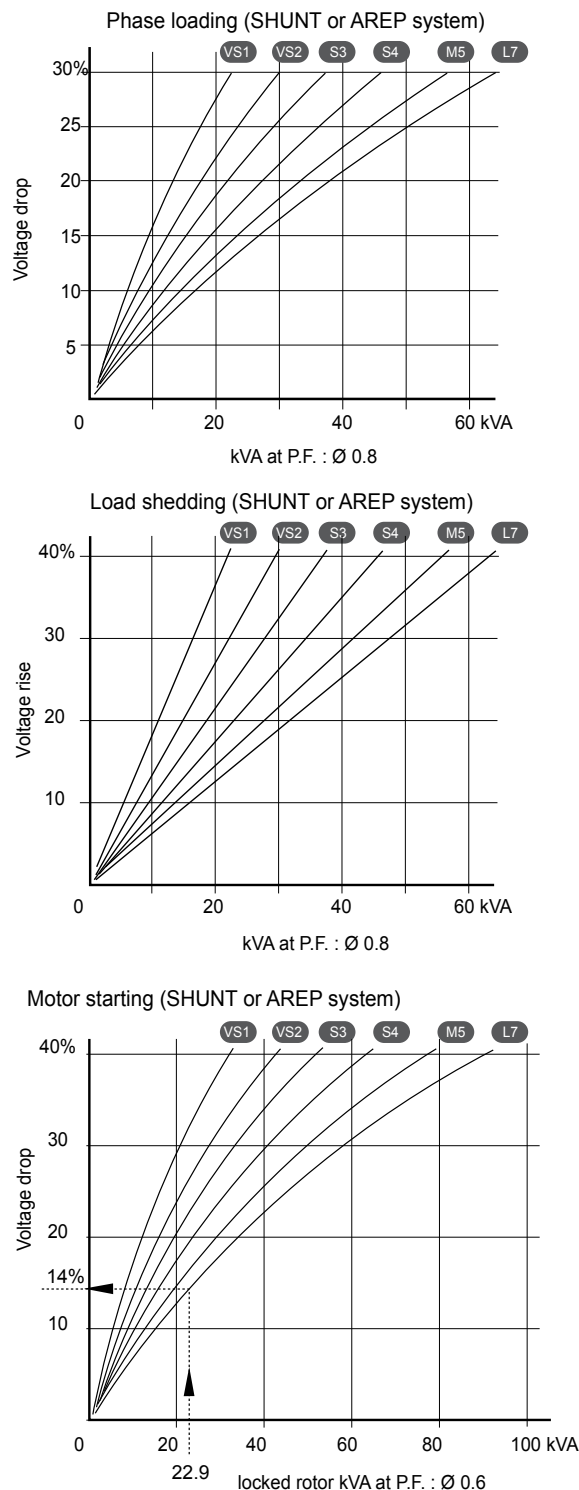
io (A) No-load excitation current (SHUNT/AREP)	0.8 / 1.1	0.8 / 1.1	0.8 / 1.1	0.8 / 1.1	0.8 / 1	0.7 / 1
ic (A) On-load excitation current (SHUNT/AREP)	2.0 / 2.7	2 / 2.8	2.1 / 2.9	2.1 / 2.9	2 / 2.7	2 / 2.7
uc (V) On-load excitation voltage (SHUNT/AREP)	25 / 18	25 / 18	26 / 19	26 / 19	24 / 18	24 / 17
ms Response time ($\Delta U = 20\%$ transient)	<300ms	<300ms	<300ms	<300ms	<300ms	<300ms
kVA Start ($\Delta U = 20\%$ cont. or $\Delta U = 30\%$ trans.) SHUNT	25	29	36	44	52	62
kVA Start ($\Delta U = 20\%$ cont. or $\Delta U = 30\%$ trans.) AREP	25	29	36	44	52	62
% Transient ΔU (on-load 4/4) SHUNT - P.F.: 0.8 _{LAG}	< 16%	< 15.2%	< 14.7%	< 13.9%	< 13.2%	< 13.2%
% Transient ΔU (on-load 4/4) AREP - P.F.: 0.8 _{LAG}	< 16%	< 15.2%	< 14.7%	< 13.9%	< 13.2%	< 13.2%
W No-load losses	460	520	550	600	660	730
W Heat dissipation	1610	1790	2040	2270	2360	2510

Low Voltage alternators 4 pole 3-phase **PARTNER**

LSA 40

10 to 23 kVA - 50 Hz / 12.5 to 28 kVA - 60 Hz

Transient voltage variation 400V - 50 Hz



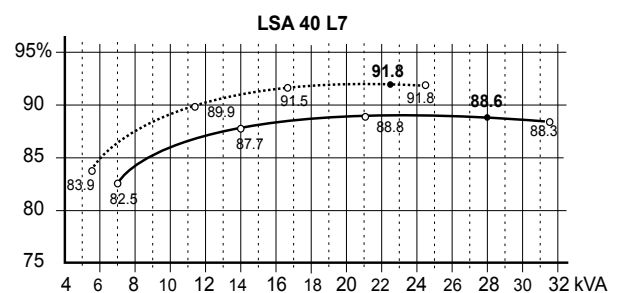
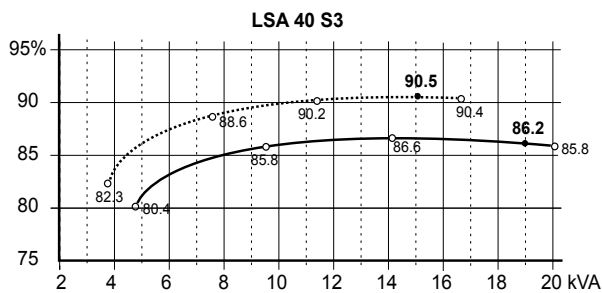
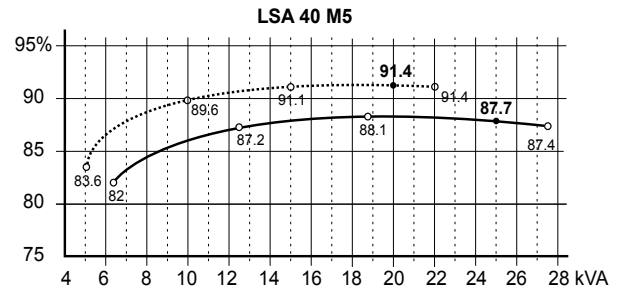
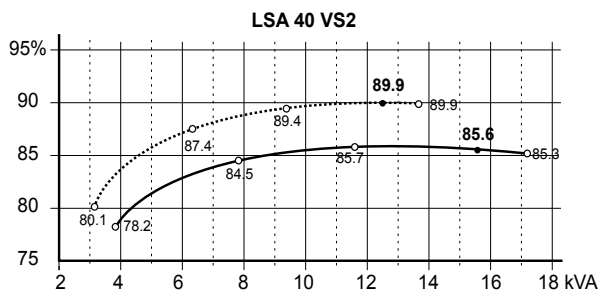
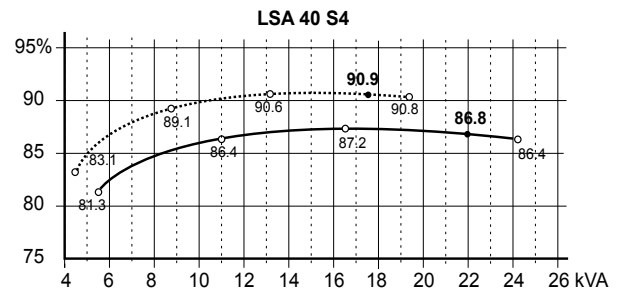
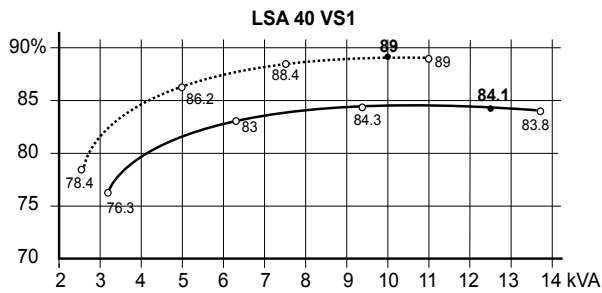
- 1) For a P.F. with a $\cos$ other than 0.6, multiply the kVA by $K = \sin P.F. / 0.8$
Example of calculation for a P.F. with a other than 0.6 : motor starting kVA calculated at P.F. : 0.4 = 20 kVA
 $\blacktriangleright \sin P.F. : 0.4 = 0.9165 \blacktriangleright K = 1.145 \blacktriangleright \text{corrected kVA} = 22.9 \text{ kVA} \blacktriangleright \text{Corresponding voltage drop for L7} = 14\%$
- 2) For a voltage U other than 400 V (Y), 230 V (Δ) at 50 Hz , multiply the kVA by $(400/U)^2$ or $(230/U)^2$.

Low Voltage alternators 4 pole 3-phase *PARTNER*

LSA 40

10 to 23 kVA - 50 Hz / 12.5 to 28 kVA - 60 Hz

Efficiencies 60 Hz (— P.F.: 0.8) (..... P.F.: 1)



Reactances (%). Time constants (ms) - Class H / 480 V

	VS1	VS2	S3	S4	M5	L7
Kcc Short-circuit ratio	0.69	0.67	0.59	0.59	0.61	0.62
Xd Direct-axis synchro. reactance unsaturated	174	180	201	204	201	195
Xq Quadrature-axis synchro. reactance unsaturated	104	108	120	122	121	117
T'do No-load transient time constant	780	858	909	953	1006	1072
X'd Direct-axis transient reactance saturated	17.9	16.8	17.8	17.2	16.1	14.6
T'd Short-circuit transient time constant	74	74	74	74	74	74
X''d Direct-axis subtransient reactance saturated	8.9	8.4	8.9	8.6	8.0	7.3
T''d Subtransient time constant	7	7	7	7	7	7
X''q Quadrature-axis subtransient reactance saturated	16.7	16.4	17.8	17.6	16.9	15.9
Xo Zero sequence reactance unsaturated	0.1	0.1	0.1	0.1	0.1	0.1
X2 Negative sequence reactance saturated	12.9	12.4	13.4	13.1	12.5	11.6
Ta Armature time constant	11	11	11	11	11	11

Other class H/480 V data

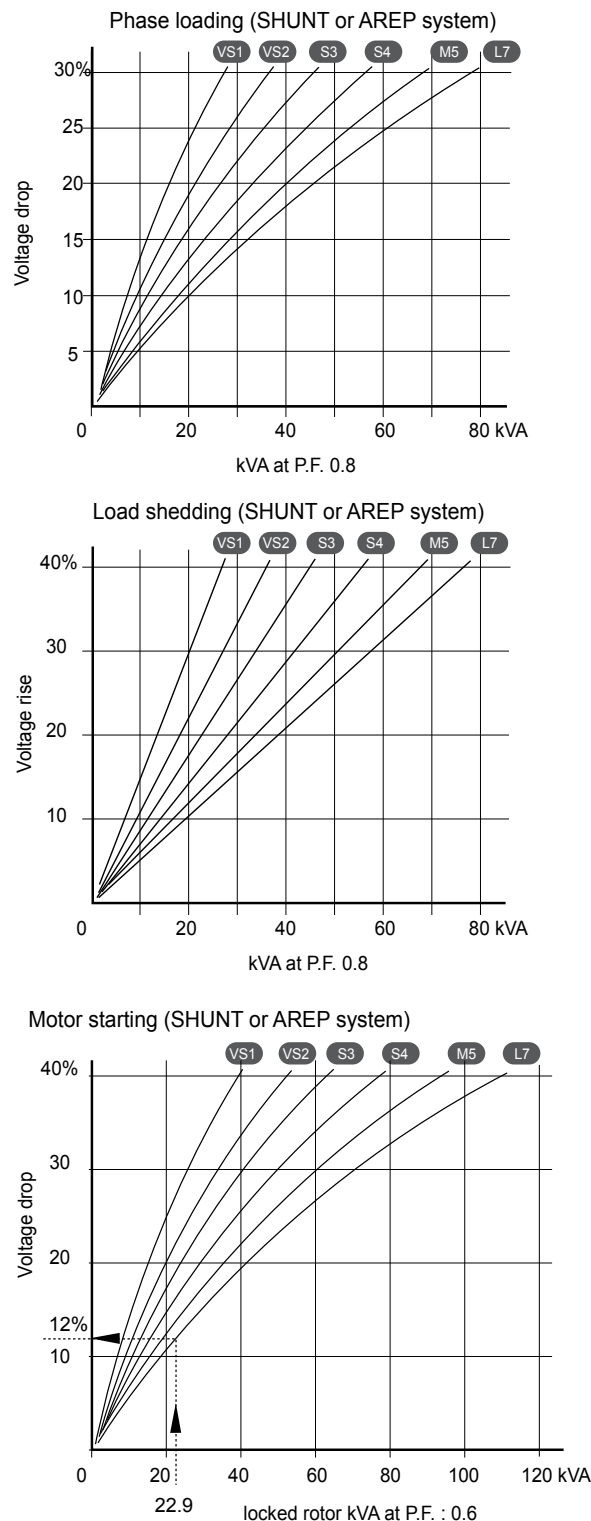
io (A) No-load excitation current (SHUNT/AREP)	0.8 / 1.1	0.8 / 1.1	0.8 / 1.1	0.8 / 1.1	0.8 / 1	0.7 / 1
ic (A) On-load excitation current (SHUNT/AREP)	2.0 / 2.8	2.0 / 2.8	2.2 / 2.9	2.2 / 2.9	2.0 / 2.8	1.9 / 2.6
uc (V) On-load excitation voltage (SHUNT/AREP)	25 / 18	25 / 18	26 / 19	26 / 19	25 / 18	24 / 17
ms Response time ($\Delta U = 20\%$ transient)	<300ms	<300ms	<300ms	<300ms	<300ms	<300ms
kVA Start ($\Delta U = 20\%$ cont. or $\Delta U = 30\%$ trans.) SHUNT	30	35	43	53	62	74
kVA Start ($\Delta U = 20\%$ cont. or $\Delta U = 30\%$ trans.) AREP	30	35	43	53	62	74
% Transient ΔU (on-load 4/4) SHUNT - P.F.: 0.8 _{LAG}	< 16.4%	< 15.4%	< 15.2%	< 14.3%	< 13.5%	< 13.3%
% Transient ΔU (on-load 4/4) AREP - P.F.: 0.8 _{LAG}	< 16.4%	< 15.4%	< 15.2%	< 14.3%	< 13.5%	< 13.3%
W No-load losses	650	730	770	840	920	1020
W Heat dissipation	1880	2080	2420	2670	2780	2870

Low Voltage alternators 4 pole 3-phase **PARTNER**

LSA 40

10 to 23 kVA - 50 Hz / 12.5 to 28 kVA - 60 Hz

Transient voltage variation 480V - 60 Hz



1) For a P.F. other than 0.6, multiply the kVA by $K = \sin P.F. / 0.6$

Example of calculation for a P.F. with a P.F. other than 0.6: motor starting kVA calculated at P.F. 0.4 = 20 kVA

► $\sin P.F. 0.4 = 0.9165$ ► $K = 1.145$ ► corrected kVA = 22.9 kVA ► Corresponding voltage drop for L7 = 12%.

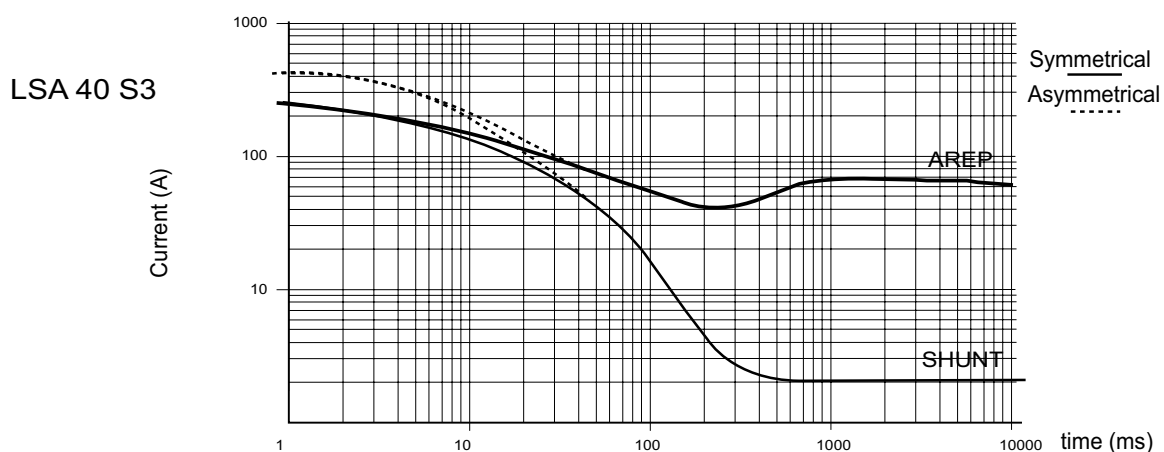
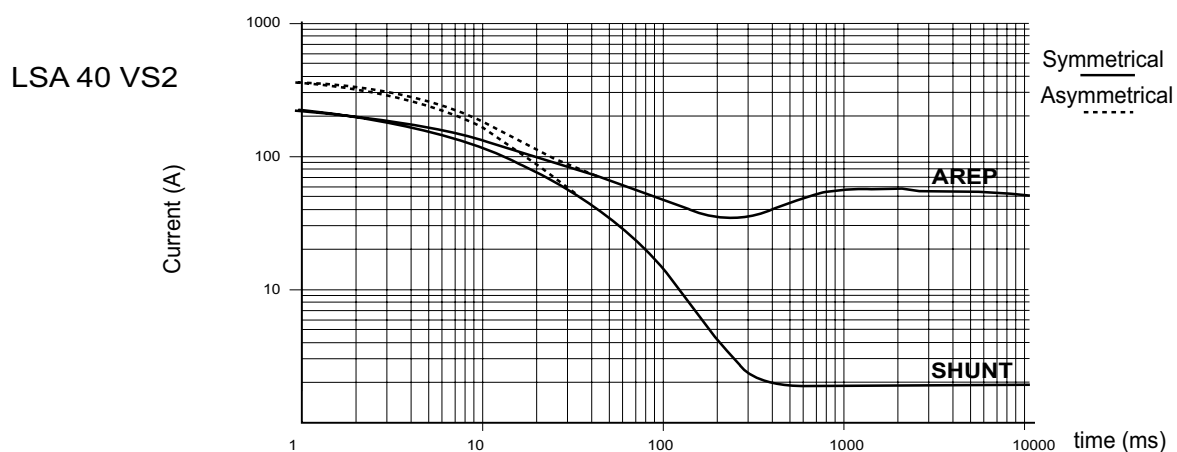
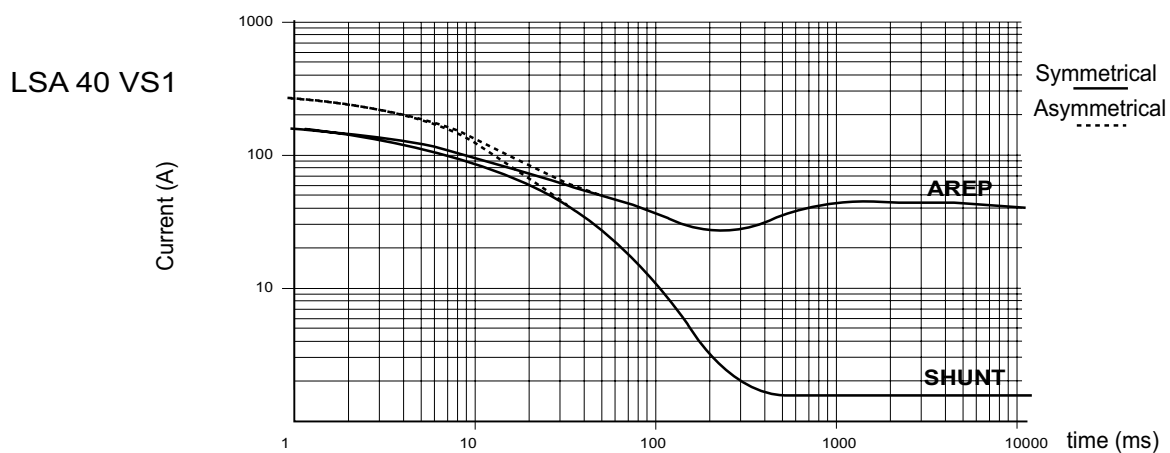
2) For a voltage U other than 480 V (Y), 277 V (Δ), 240 V (YY) at 60 Hz, multiply the kVA by $(480/U)^2$ or $(277/U)^2$ or $(240/U)^2$.

Low Voltage alternators 4 pole 3-phase *PARTNER*

LSA 40

10 to 23 kVA - 50 Hz / 12.5 to 28 kVA - 60 Hz

3-phase short-circuit curves at no load and rated speed (star connection Y)



Influence due to connection

Curves shown are for star (Y) connection.

For other connections, use the following multiplication factors:

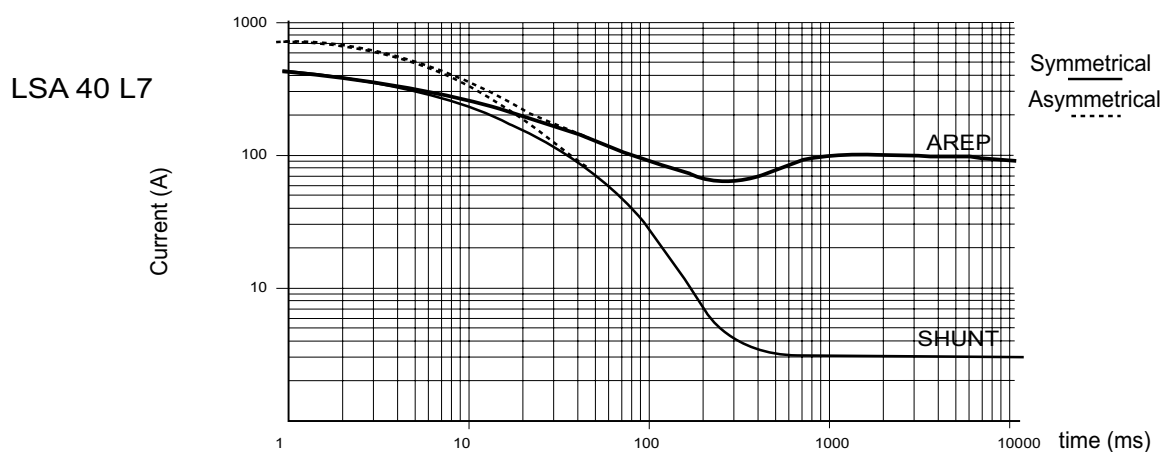
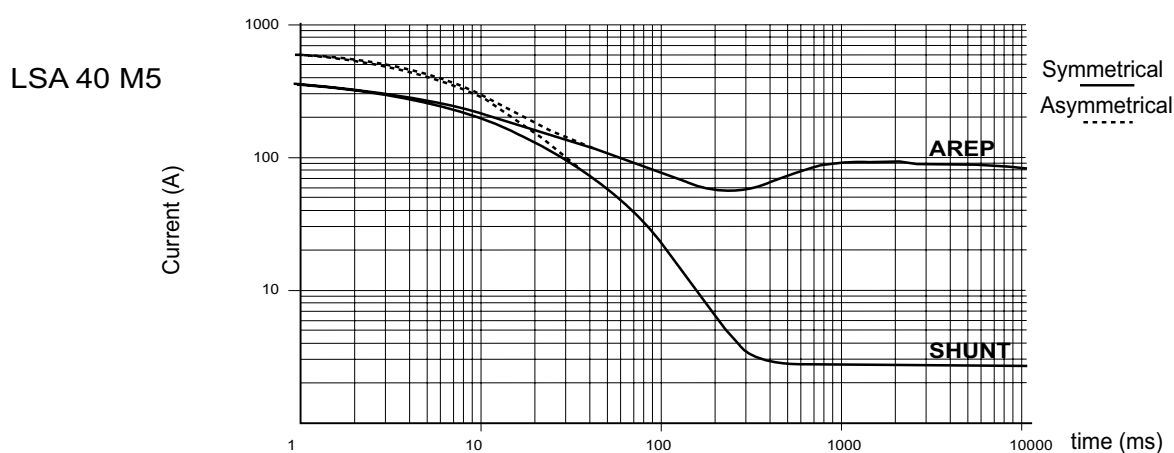
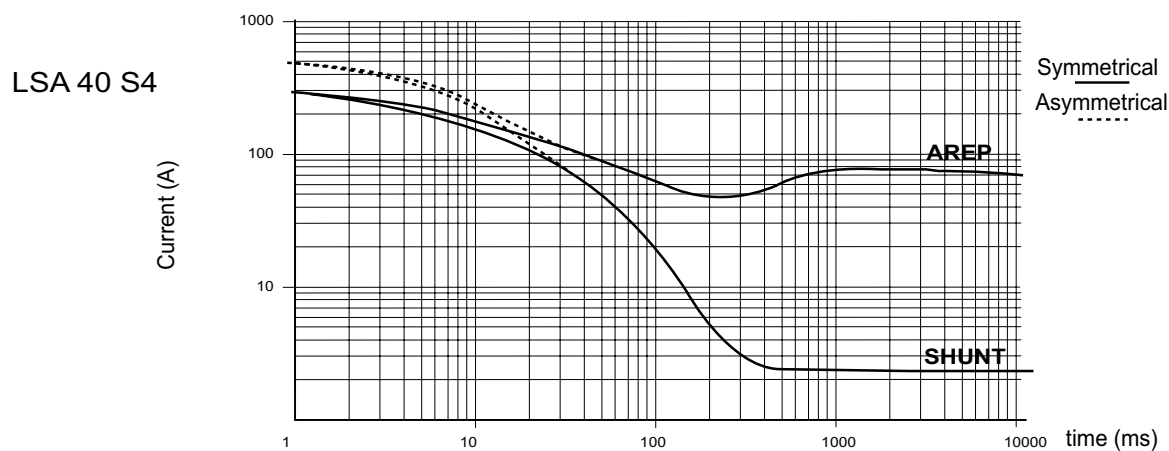
- Series delta: Current value x 1.732
- Parallel star: Current value x 2

Low Voltage alternators 4 pole 3-phase *PARTNER*

LSA 40

10 to 23 kVA - 50 Hz / 12.5 to 28 kVA - 60 Hz

3-phase short-circuit curves at no load and rated speed (star connection Y)



Influence due to short-circuit

Curves are based on a three-phase short-circuit.

For other types of short-circuit, use the following multiplication factors

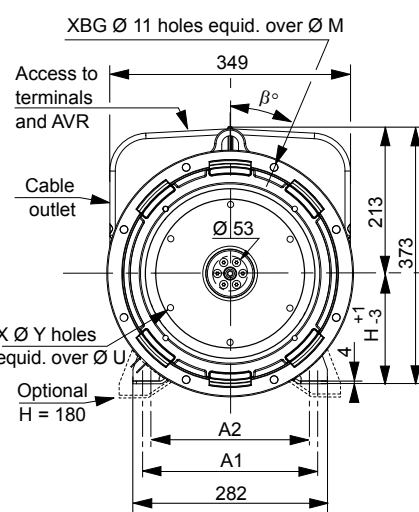
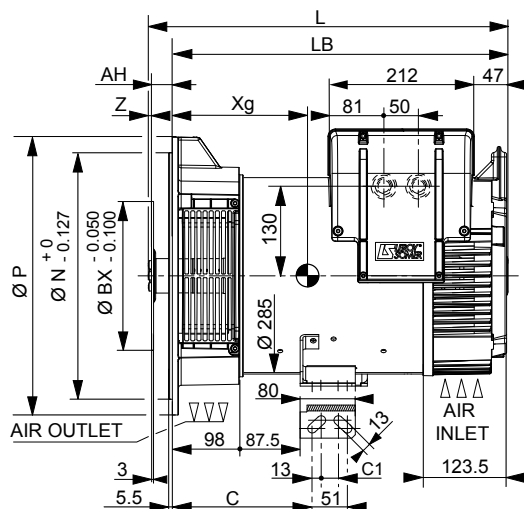
	3-phase	2-phase L/L	1-phase L/N
Instantaneous (max.)	1	0.87	1.3
Continuous	1	1.5	2.2
Maximum duration (AREP/PMG)		1.5	

10 to 23 kVA - 50 Hz / 12.5 to 28 kVA - 60 Hz

Detail of S.A.E. 5 flange

Dimensions and labels:

- L
- LB
- AH
- Z
- Xg
- Ø P
- Ø N $+0 -0.127$
- Ø BX $-0.050 -0.100$
- AIR OUTLET
- 3
- 5.5
- 203



Coupling			
Flange	3	4	5
Flex plate			
11 1/2	x	-	-
10	x	x	-
7 1/2	-	x	x
6 1/2	-	x	x

Flex plate (mm)						
S.A.E.	BX	U	X	Y	AH	Z
11 1/2	352.42	333.38	8	11	39.6	0
10	314.32	295.28	8	11	53.8	0
8	263.52	244.48	6	11	62	0
7 1/2	241.3	222.25	8	9	30.2	4.5
6 1/2	215.9	200.02	6	9	30.2	4.5

Technical drawing of a mechanical assembly showing a cross-section of a shaft with a pulley and a coupling. Dimensions include radii X_r and L_r , and diameters $\varnothing 18$, $\varnothing 50$, $\varnothing 52$, $\varnothing 55$, $\varnothing 41$, and $\varnothing 25$.

Centre of gravity: Xr (mm), Rotor length: Lr (mm), Weight: M (kg), Moment of inertia: J (kgm²): (4J = MD²)																				
Type	Flex plate S.A.E. 6 1/2				Flex plate S.A.E. 7 1/2				Flex plate S.A.E. 8				Flex plate S.A.E. 10				Flex plate S.A.E. 11 1/2			
	Xr	Lr	M	J	Xr	Lr	M	J	Xr	Lr	M	J	Xr	Lr	M	J	Xr	Lr	M	J
LSA 40 VS1	211.7	428	25.54	0.0779	211.7	428	25.7	0.0802	243.5	428	26	0.0847	238.3	428	26.5	0.0964	221.1	428	27	0.1080
LSA 40 VS2	221.7	428	27.95	0.0867	221.7	428	28.11	0.0890	253.5	428	28.41	0.0935	248.3	428	28.91	0.1052	231.1	428	29.41	0.1168
LSA 40 S3	229.2	458	30.32	0.0936	229.2	458	30.48	0.0959	261	458	30.78	0.1004	255.8	458	31.28	0.1121	238.6	458	31.78	0.1237
LSA 40 S4	236.7	458	32.23	0.1004	236.7	458	32.39	0.1027	268.5	458	32.69	0.1072	263.3	458	33.19	0.1189	246.1	458	33.69	0.1305
LSA 40 M5	246.7	478	35.26	0.1102	246.7	478	35.42	0.1125	278.5	478	35.72	0.1170	273.3	478	36.22	0.1287	256.1	478	36.72	0.1403
LSA 40 L7	261.7	508	39.47	0.1237	261.7	508	39.63	0.1260	293.5	508	39.93	0.1305	288.3	508	40.43	0.1422	271.1	508	40.93	0.1538

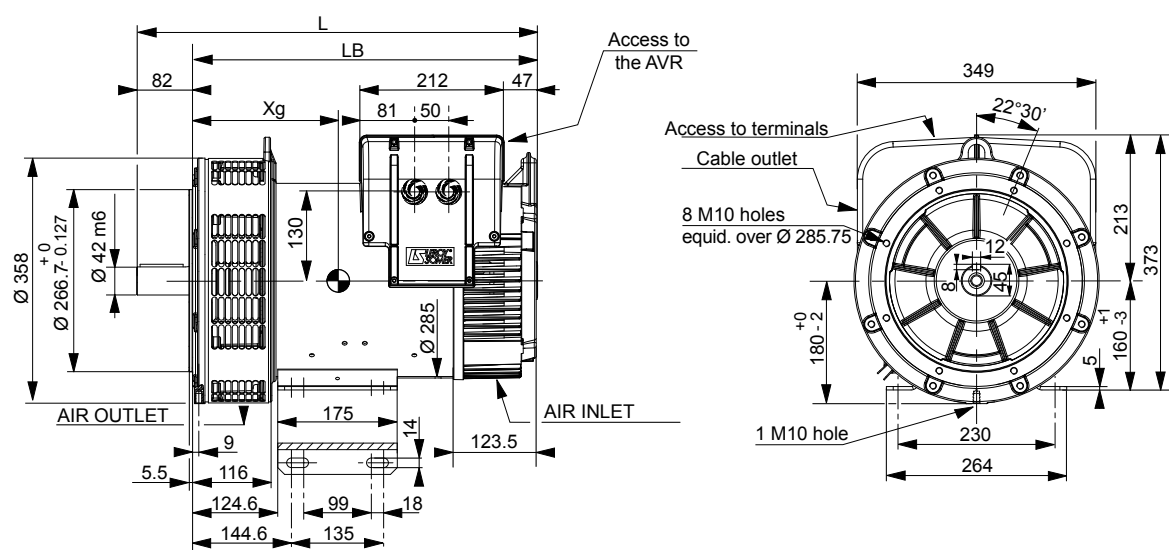
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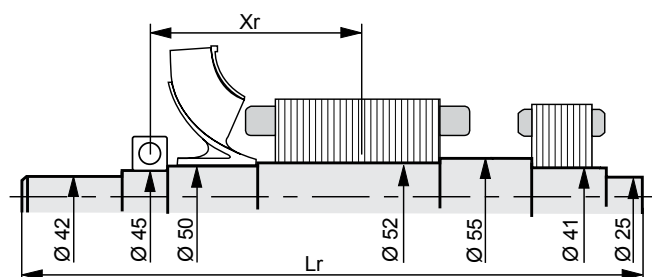
LSA 40

10 to 23 kVA - 50 Hz / 12.5 to 28 kVA - 60 Hz

Two bearing dimensions



Dimensions (mm)				
Type	L	LB	Xg	Weight (kg)
LSA 40 VS1	505	423	198	82
LSA 40 VS2	505	423	208	89
LSA 40 S3	535	453	216	96
LSA 40 S4	535	453	233	101
LSA 40 M5	555	473	233	109
LSA 40 L7	585	503	248	121

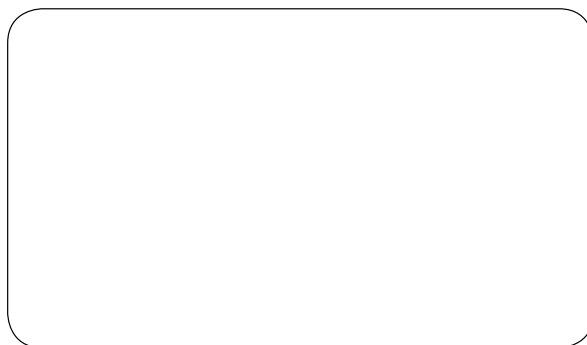


Torsional analysis data

Centre of gravity: Xr (mm), Rotor length: Lr (mm), Weight: M (kg), Moment of inertia: J (kgm ²): (4J = MD ²)				
Type	Xr	Lr	M	J
LSA 40 VS1	176.5	450.2	25.38	0.0731
LSA 40 VS2	186.5	450.2	27.79	0.0819
LSA 40 S3	194	480.2	30.16	0.0888
LSA 40 S4	201.5	480.2	32.07	0.0956
LSA 40 M5	211.5	500.2	35.10	0.1054
LSA 40 L7	226.5	530.2	39.31	0.1189

NOTE : Dimensions are for information only and may be subject to modifications. Contractuel 2D drawings can be downloaded from the Leroy-Somer site, 3D drawing files are available upon request.

Contact



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